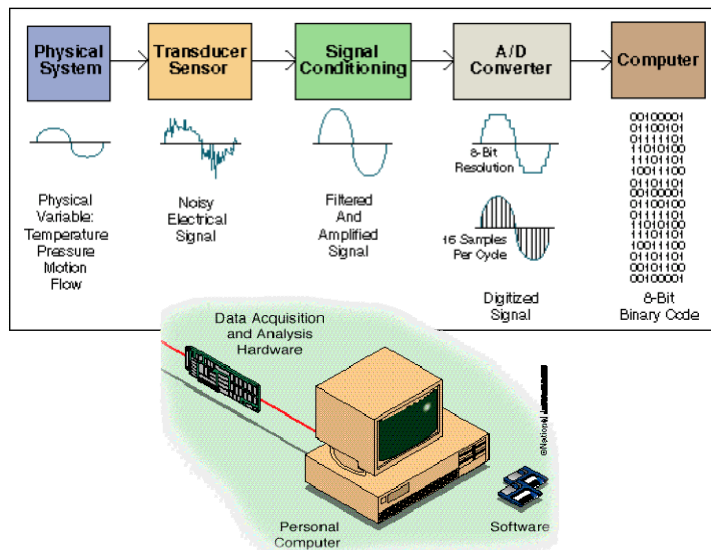


Data acquisition and instrumentation

START Lecture
Sam Sadeghi

Data acquisition

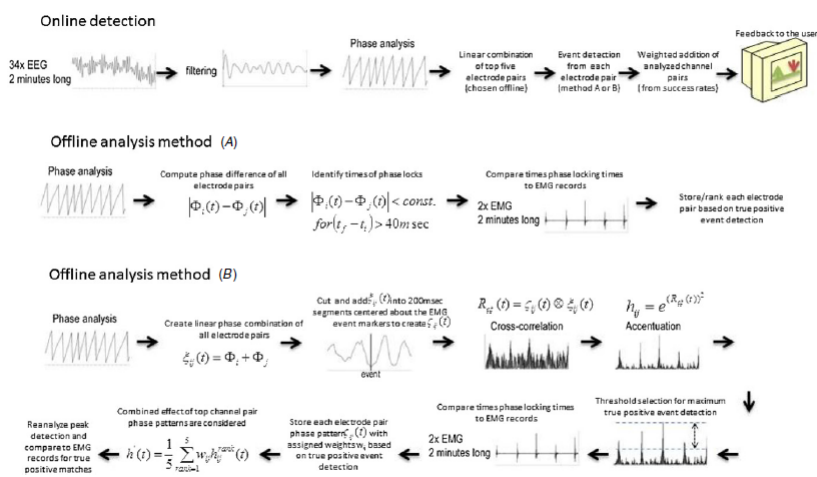


Humanistic Intelligence

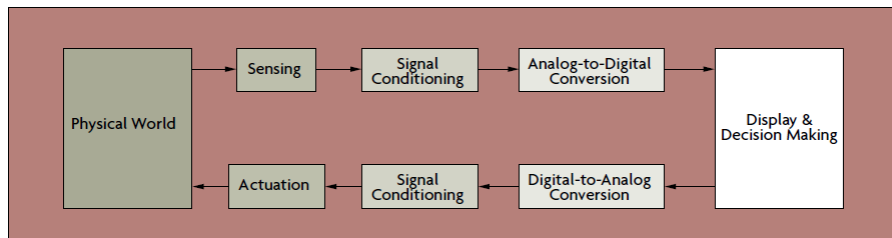
Body as a transducer,
data acquisition and
signal processing
machine



Analysis of physiological data

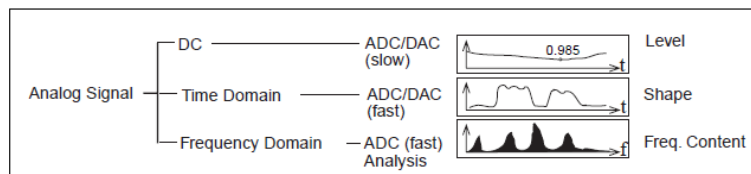


Data acquisition and control



Define the signal

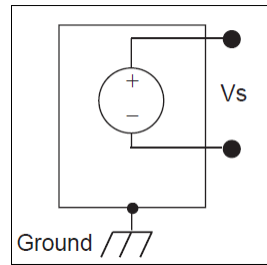
- Knowing your signal in choosing the right hardware, system and be cost effective



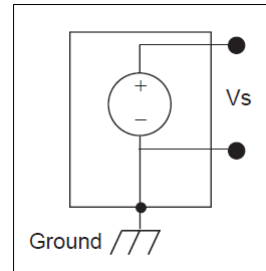
- Review of AC and DC signals
- Voltage and current dividers

Signal reference

- Floating source

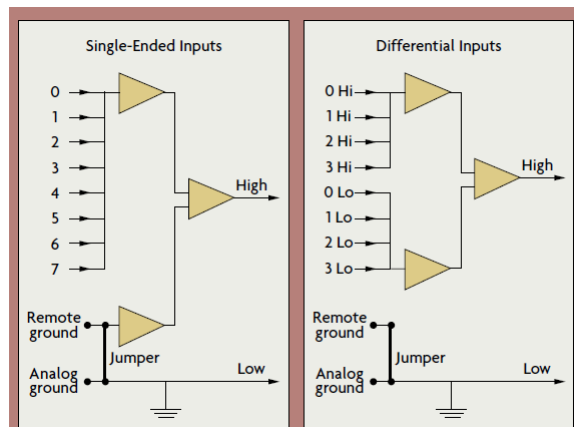


- Grounded source



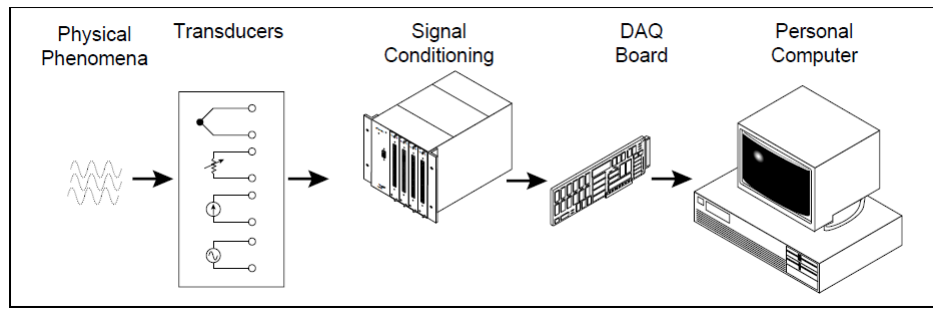
Single and differential inputs

- ground-loop induced voltage appears in both ends of differential signal and is rejected



Signal conditioning

- sensors and transducers output signals that must be conditioned before a DAQ board or device can effectively and accurately acquire the signal

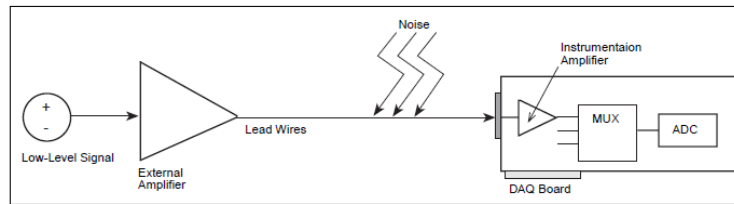


Signal conditioning

- **Amplification**
 - Boosting the input signal uses as much of the ADC input range as possible
 - Amplifying these low-level analog signals directly on the DAQ board also amplifies any noise
 - amplify the signal as close to the source as possible
- **Filtering and Averaging**
- **Isolation**
 - potential difference in the grounds on both inputs to DAQ system show as *common-mode voltage*
 - optical, magnetic, or capacitive isolators
 - convert voltage to a frequency, transmit across a transformer or capacitor without a direct physical connection, converted back to a voltage value
- **Multiplexing**
 - expand the input/output (I/O) capabilities

Amplification

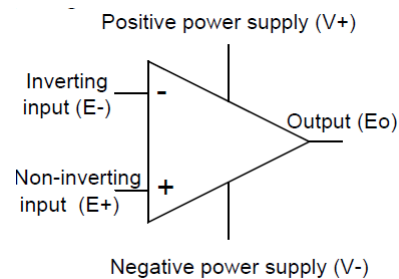
- Amplifying Signals near the Source Increases Signal-to-Noise Ratio



- Review of Op-Amps

Operational amplifiers

- Op-amps are composed of carefully matched sets of transistors and resistors



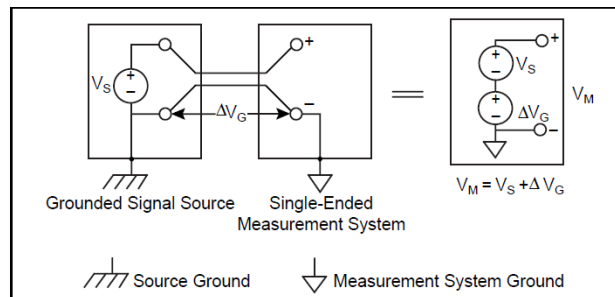
Op-amps

Characteristics of op-amps are:

1. very high input impedance (10^6 ohms or more),
2. high open-loop gain ($A > 10^5$ or more),
3. low output impedance (able to deliver V_o into small resistances),
4. fast response (slew rates of up to several volts per microsecond),
5. able to reject common mode inputs

Isolation and filtering

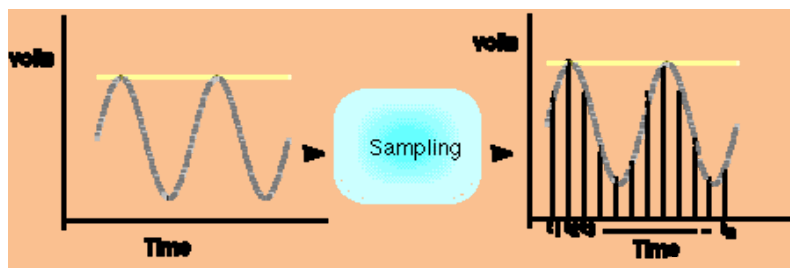
- Isolate the transducer signals from the computer for safety purposes
- Avoid differences in ground potentials (differential measurement)



- Filter unwanted signals or noise from the signal you are trying to measure
- filter on low-rate (or slowly-changing) signals, like temperature, or eliminate higher-frequency signals (60Hz, aliasing)

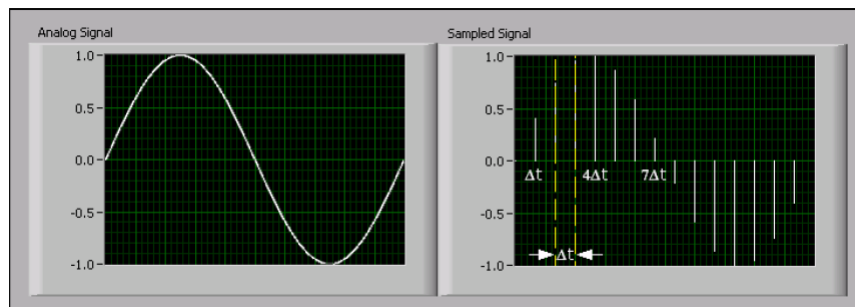
Sampling

- The data is acquired by an ADC using a process called sampling.
- taking a sample of the signal at discrete times.
- rate at which the signal is sampled is known as *sampling frequency*



Digital representation

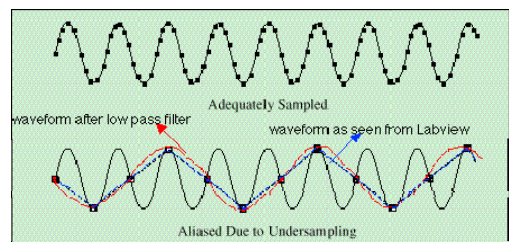
- The signal $x(t)$ can be represented by the discrete set of samples



$$X = \{x[0], x[1], x[2], x[3], \dots, x[N-1]\}$$

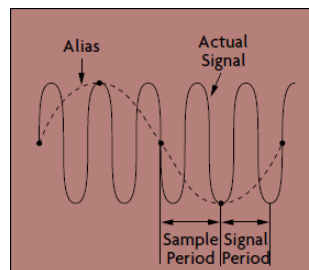
Sampling rate

- The minimum sampling frequency required to represent the signal should at least be *twice the maximum frequency* of the analog signal under test (this is called the Nyquist rate).

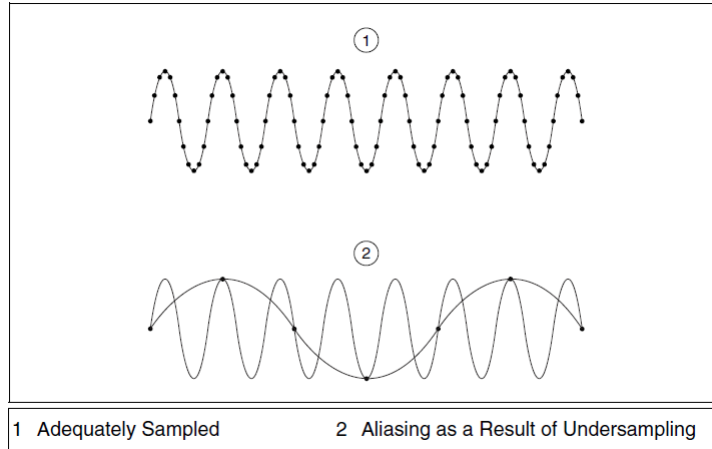


Aliasing

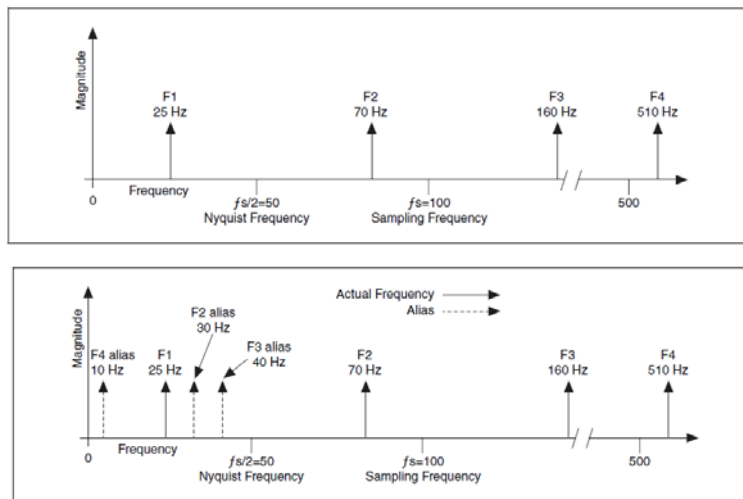
- Sampling too slowly results in aliasing, which is a misrepresentation of the analog signal.
- Undersampling causes the signal to appear as if it has a different frequency than it actually does.



Aliasing



Aliased frequency



Aliased frequency

Alias Freq. = ABS (Closest Int. Mult. of Sampling Freq. – Input Freq.)

where ABS means the absolute value. For example,

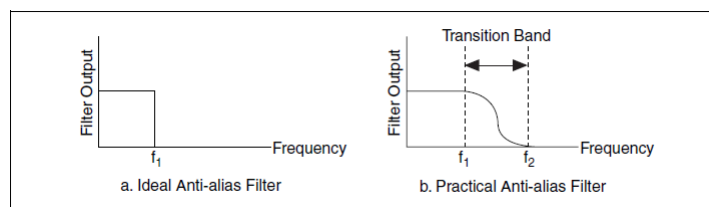
$$\text{Alias } F_2 = |100 - 70| = 30 \text{ Hz}$$

$$\text{Alias } F_3 = |(2)100 - 160| = 40 \text{ Hz}$$

$$\text{Alias } F_4 = |(5)100 - 510| = 10 \text{ Hz}$$

Anti-aliasing filters

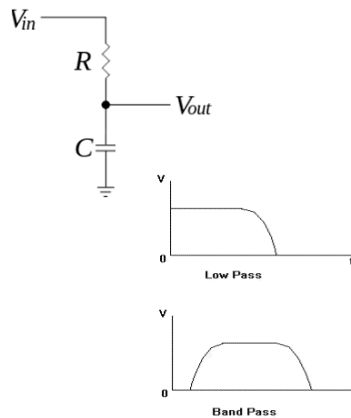
- lowpass filter is added before the ADC
- prevents the aliasing components from being sampled by attenuating the higher frequencies



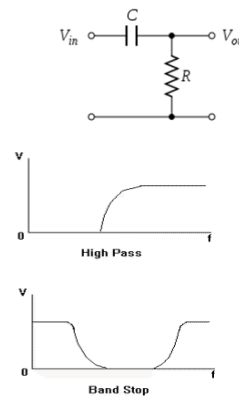
Filters

- Review of capacitors and filters

Low pass

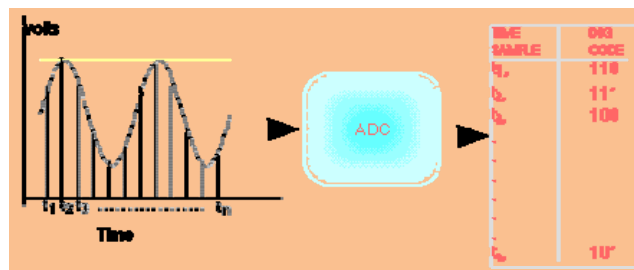


High pass

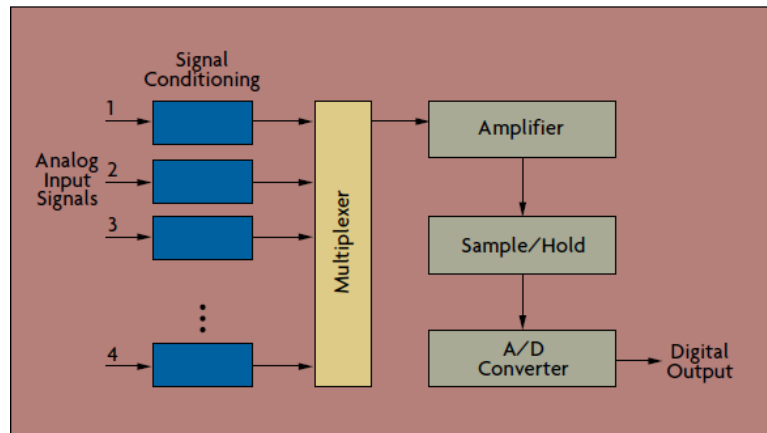


Analog to Digital conversion

- Sampled analog signal has to be converted into a digital code.
- This process is called analog to digital conversion.



Analog input flow-diagram



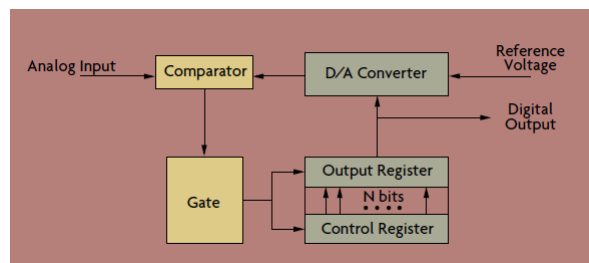
A/D conversion methods

Figure 1-6: Alternative A/D Converter Designs

DESIGN	SPEED	RESOLUTION	NOISE IMMUNITY	COST
Successive approximation	Medium	10-16 bits	Poor	Low
Integrating	Slow	12-18 bits	Good	Low
Ramp/counting	Slow	14-24 bits	Good	Medium
Flash/parallel	Fast	4-8 bits	None	High

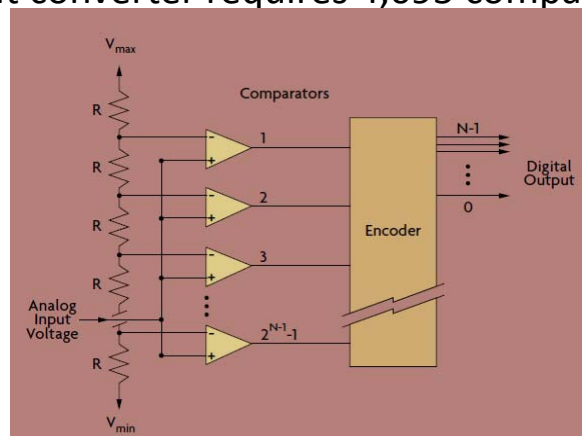
successive approximation

- internal digital-to-analog (D/A) converter
- single comparator => which of two voltages is higher



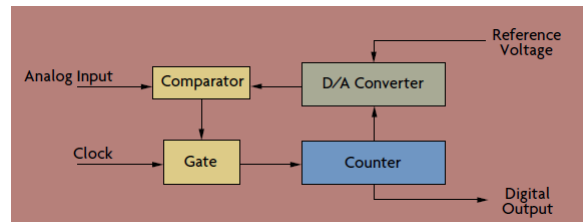
Flash/parallel

- multiple comparators in parallel
- 12-bit converter requires 4,095 comparators



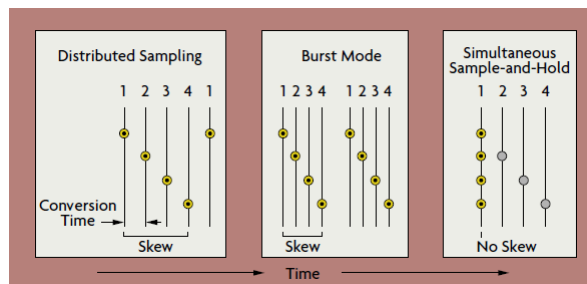
Ramp and integration

- comparator circuit and progressively increments a digital counter
- integrates an unknown input voltage for a specific period of time, then integrates it back down to zero.



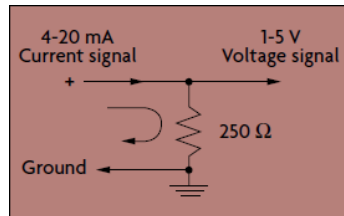
multiplexing

- single A/D converter often is shared among multiple input channels via a switching mechanism called a multiplexer.
- Sample and hold can be used to correct phase

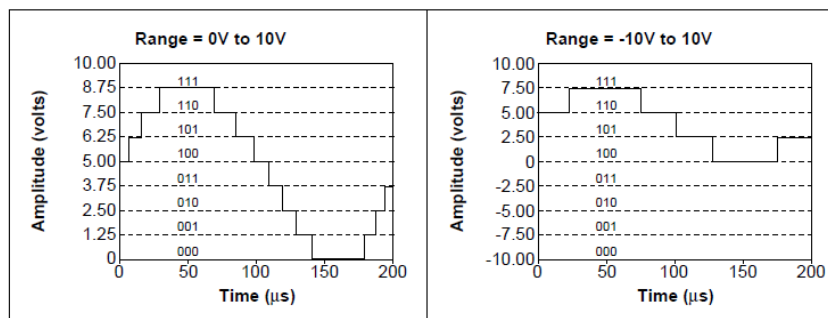


Signal conditioning

- Amplification
- Conversion
- Signal scaling (dynamic range)



Device range



- 3-bit ADC range of 0 to 10 volts or -10 to 10V
- smallest detectable voltage increases from 1.25 to 2.50 volts

Range and resolution

$$\text{codewidth} = \frac{\text{device range}}{2^{\text{resolution}}}$$

$$\frac{\text{device range}}{2^{\text{resolution}}} = \frac{10}{2^{12}} = 2.4 \text{ mV}$$

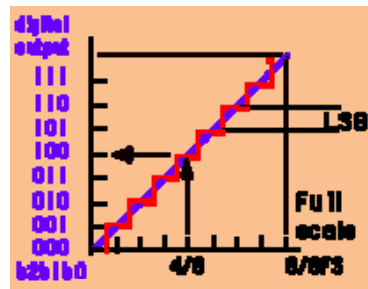
$$\frac{\text{device range}}{2^{\text{resolution}}} = \frac{20}{2^{12}} = 4.8 \text{ mV}$$

ADC Resolution

- Precision of the analog input signal converted into digital format is dependent upon the number of bits the ADC uses.
- The *resolution* is a function of the number of ADC bits
- higher the resolution, the higher the number of divisions the voltage range is broken into $2^{\text{\#bits}}$
- Higher bits => smaller increments of the input signals detected
- LSB or least significant bit is defined as the minimum increment of the voltage that a ADC can convert.
- LSB varies with the operating input voltage range of the ADC.

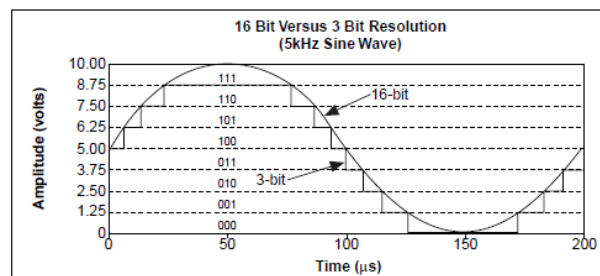
Voltage resolution

- 10V signal with 3-bit ADC corresponds to $10/2^3=1.25V$ LSB
- 12 bit ADC LSB is $10/2^{12}=10/4096=2.44mV$.



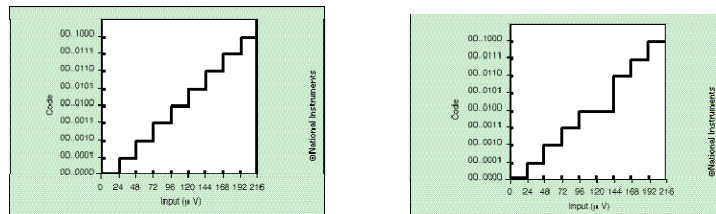
Resolution

- The number of bits used to represent an analog signal determines the *resolution* of the ADC



Non linearity

- digital codes may not increment linearly with variation of analog input



Scan rate

- Related to number of bits
- Op-amp comparator
- Number of channels
- Required resolution

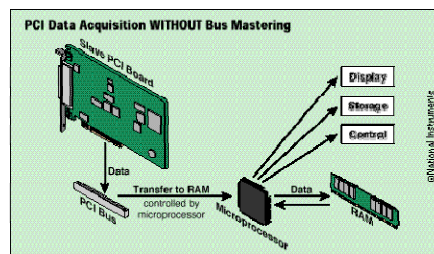
Settling time

- Analog signal is:
 - selected by a multiplexer
 - Amplified
 - converted by the ADC.
- The amplifier must be in sync with multiplexer and ADC
- If wait time is insufficient ADC can convert the signal that is still in transition from the previous value
- settling time changes with sampling rate and the gain of the DAQ board

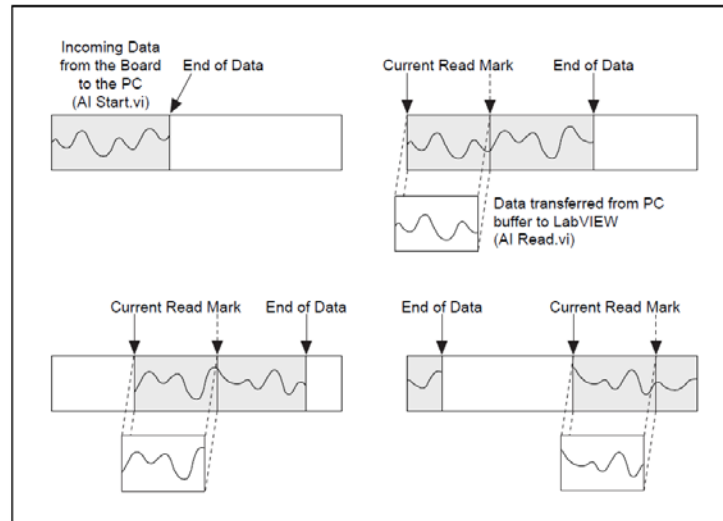
Data transfer

- DAQ boards communicate with PC through high speed data bus

Bandwidth Table (Mbits/Sec)	
PCI	1056 Mb/s
AGP 8X	2,133 Mb/s
PCI Express 1x	2,500 Mb/s
PCI Express 4x	10,000 Mb/s
PCI Express 8x	20,000 Mb/s
PCI Express 16x	40,000 Mb/s
IDE (ATA100)	800 Mb/s
IDE (ATA133)	1064 Mb/s
SATA	1500 Mb/s
SATA II	3000 Mb/s
SATA 6	6000 Mb/s
Firewire 400	400 Mb/s
USB 1	12 Mb/s
USB 2	480 Mb/s
USB 3	4,800 Mb/s
Gigabit Ethernet	1000 Mb/s

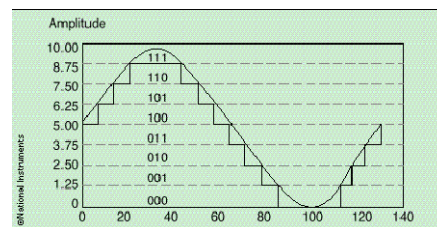


Buffered acquisition



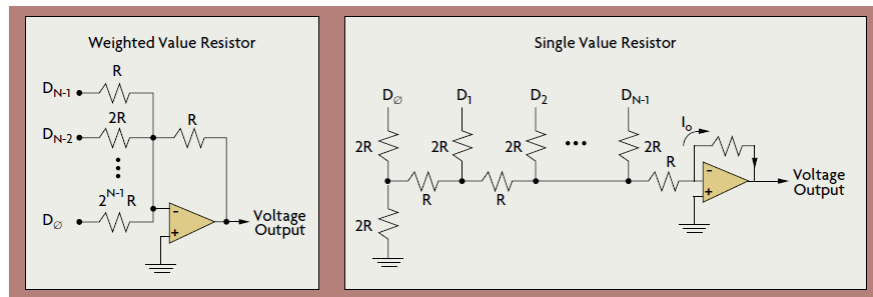
Digital to Analog conversion

- Digital to analog converters (DAC) can generate an analog output from a digital input.
- Allows the board to generate analog signals, both dc and ac voltages.
- Control



D/A Circuitry

- Drop in (or drop out, depending on whether the bit is 1 or 0) a series of resistors from a circuit driven by a reference voltage



Signal processing

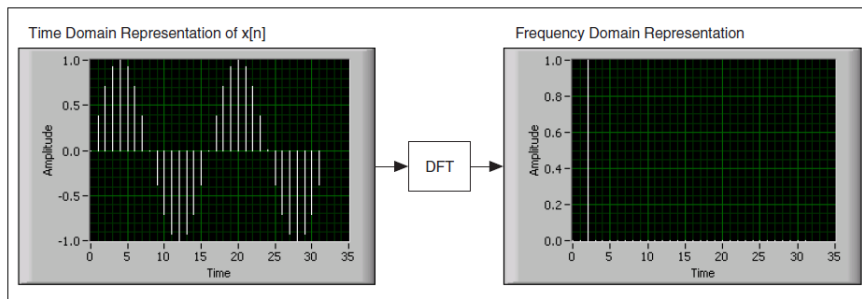
- samples of a signal obtained from a DAQ device constitute the time-domain representation of the signal
- May want to know the frequency content of a signal etc.

$$f(t) = \int_{-\infty}^{\infty} F(f) e^{i2\pi ft} df$$

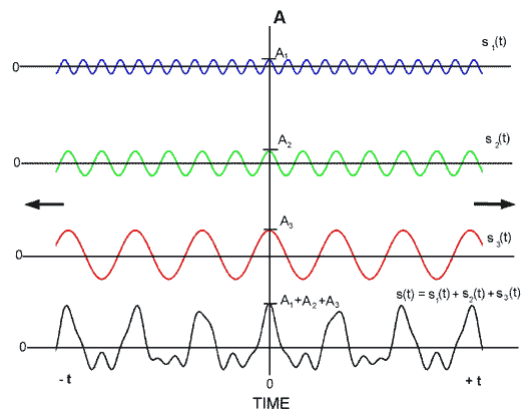
$$F(f) = \int_{-\infty}^{\infty} f(t) e^{-i2\pi ft} dt$$

Fourier transform

- algorithm used to transform samples of the data from the time domain into the frequency domain (DFT = discrete Fourier transform)



Signal in the time domain made up of separate cosinusoids



DFT

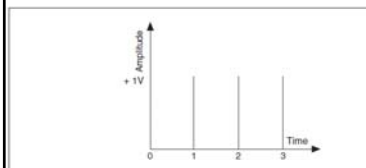
$$\Delta t = \frac{1}{f_s} \quad \Delta f = \frac{f_s}{N} = \frac{1}{N\Delta t}$$

- Δf frequency resolution
- To increase the frequency resolution (smaller Δf)
 - => increase the number of samples N with f_s constant
 - => decrease the sampling frequency f_s with N constant.

DFT

$$X_k = \sum_{i=0}^{N-1} x_i e^{-j2\pi i k / N} \quad \text{for } k = 0, 1, 2, \dots, N-1$$

$$\exp(-j\theta) = \cos(\theta) - j\sin(\theta)$$



Each of the samples has a value +1, giving the time sequence

$$x[0] = x[1] = x[2] = x[3] = 1$$

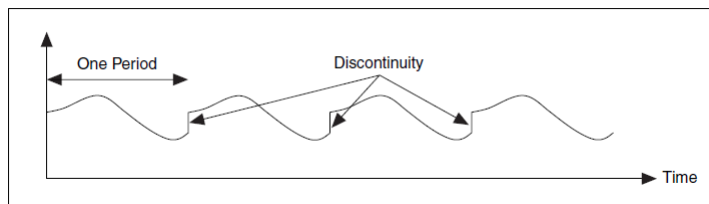
$$X[0] = \sum_{i=0}^{N-1} x_i e^{-j2\pi i 0 / N} = x[0] + x[1] + x[2] + x[3] = 4$$

$$X[1] = x[0] + x[1] \left(\cos\left(\frac{\pi}{2}\right) - j\sin\left(\frac{\pi}{2}\right) \right) + x[2] \left(\cos(\pi) - j\sin(\pi) \right) +$$

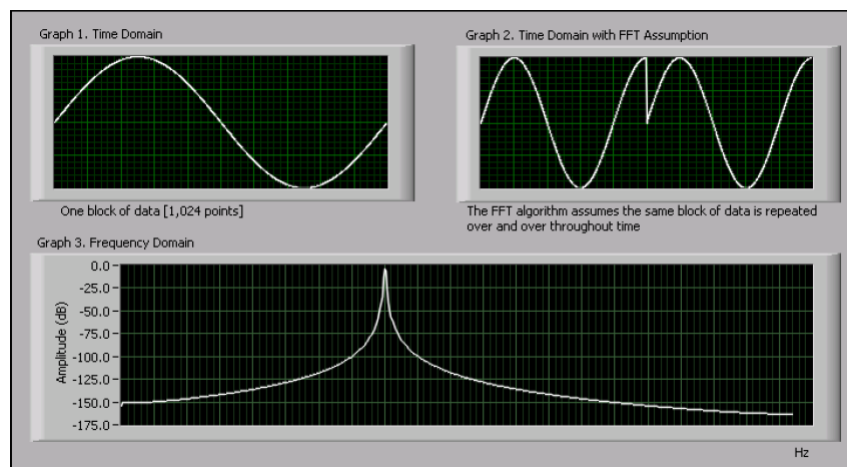
$$x[3] \left(\cos\left(\frac{3\pi}{2}\right) - j\sin\left(\frac{3\pi}{2}\right) \right) = (1 - j - 1 + j) = 0$$

smoothing

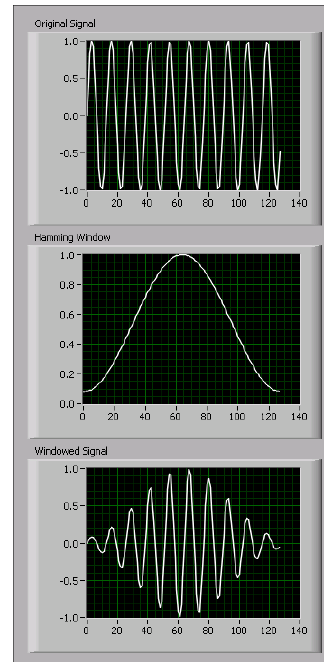
- finite number of samples of the signal acquired
- DFT/FFT assumes signal to be a single period of a periodically repeating waveform



spectral leakage



Windowing signals



software

- Acquire data at specified sampling rate
- Acquire data in the background while processing in foreground
- Stream data to and from disk
- Integrate different DAQ boards in a computer and use various functions of a DAQ board from a single user interface.
- Analyze data
- Provide feedback and control

Virtual instruments

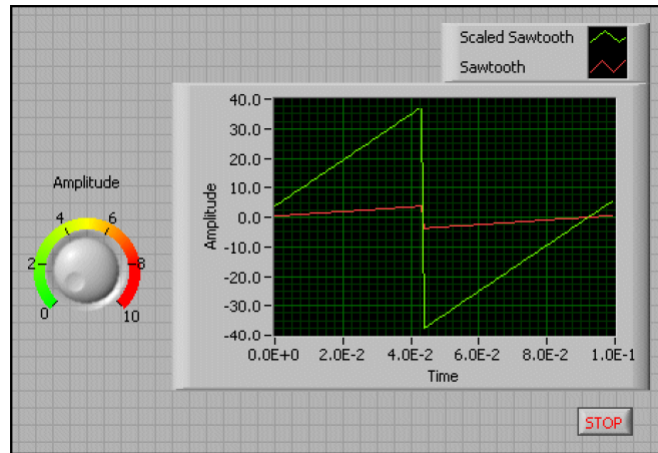
- LabVIEW programs are called virtual instruments, or VIs
- appearance and operation imitate physical instruments, such as oscilloscopes and multimeters.
- VI uses functions that manipulate input from the user interface or other sources and display that information
- move or store files to locations or computers.

Components of a VI

A VI contains the following three components:

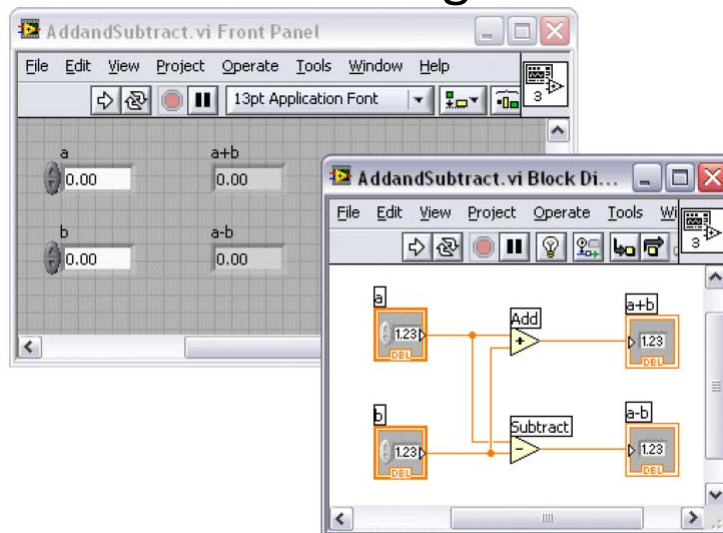
- Front panel—Serves as the user interface.
- Block diagram—Contains the graphical source code that defines the functionality of the VI.
- Icon and connector pane—Identifies the interface to the VI so that you can use the VI in another VI. A VI within another VI is called a subVI. A subVI corresponds to a subroutine in text-based programming languages.

Front panel



- controls and indicators, which are the interactive input and output terminals of the VI

Block diagram



Connector pane

- connector pane is a set of terminals that correspond to the controls and indicators of that VI, similar to the parameter list of a function call in text-based programming languages
- After you build a VI and create its icon and connector pane, you can use it as a subVI

